

DIMENSIONAL ANALYSIS

Recap: Preliminaries

- Dimension of product is the product of dimensions
- Only quantities with equal dimensions can be added or equated.

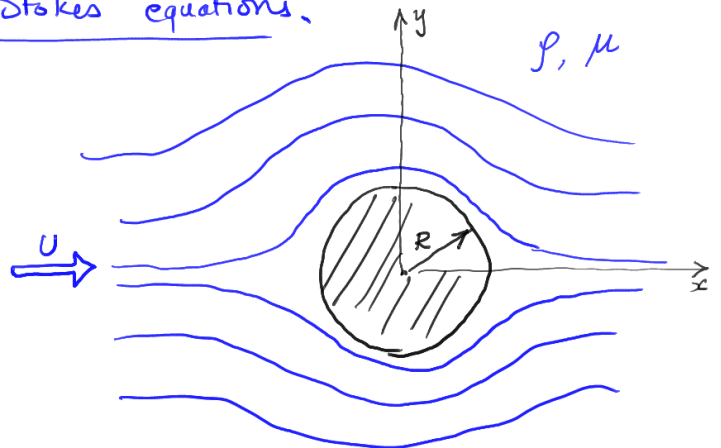
List of topics

- Non-dimensionalizing the Navier-Stokes equations.
- Deducing dependence on parameters without solving PDEs.

1. Non-dimensionalizing the Navier-Stokes equations.

Eg. Flow past a cylinder.

Find the drag (per unit depth) on a cylinder of radius R immersed in an incompressible fluid (density ρ , viscosity μ) flowing with speed U .



Mathematical formulation

Fluid velocity $\underline{u} = (u, v)$ and pressure p satisfy the incompressible N-S equations,

$$\rho \left[\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right] = -\frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right).$$

$$\rho \left[\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right] = -\frac{\partial p}{\partial y} + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0.$$

Solve these equations w/ boundary conditions

$$\underline{u}(|x| \rightarrow \infty, t) = U \hat{e}_x$$

$$\underline{u}(|x|=R, t) = \underline{0}. \quad \text{no-slip}$$

Suppose a steady solution is found. Then the drag per unit length is

$$D = \int_{\partial\Omega} \hat{e}_x \cdot \underline{T} \cdot \hat{n} \, dA \quad \text{where } \underline{T} = -p\mathbf{I} + \mu(\nabla \underline{u} + \nabla \underline{u}^T).$$

Given parameters : ρ, U, R, μ .

Use these to rescale dependent and independent variables.

$$t = (R/U) \tilde{t}$$

$$(u, v) = U(\tilde{u}, \tilde{v}), \quad p = \rho U^2 \tilde{p} \quad \left[\text{Also possible } p = \frac{\mu U}{R} \tilde{p} \right].$$

$$(x, y) = R(\tilde{x}, \tilde{y})$$

↑ dimensionless variables
characteristic scales.

$$\frac{\mu U/R^2}{\rho U^2/R} = \frac{\mu}{\rho U R} \left/ \rho \left[\frac{U}{R/U} \frac{\partial \tilde{u}}{\partial \tilde{t}} + \frac{U^2}{R} \tilde{u} \frac{\partial \tilde{u}}{\partial \tilde{x}} + \frac{U^2}{R} \tilde{v} \frac{\partial \tilde{u}}{\partial \tilde{y}} \right] = \left(\frac{\rho U^2}{R} \right) \left(-\frac{\partial \tilde{p}}{\partial \tilde{x}} \right) + \frac{\mu U}{R^2} \left(\frac{\partial^2 \tilde{u}}{\partial \tilde{x}^2} + \frac{\partial^2 \tilde{u}}{\partial \tilde{y}^2} \right) \right.$$

Rewrite as

$$\frac{\partial \tilde{u}}{\partial \tilde{t}} + \tilde{u} \frac{\partial \tilde{u}}{\partial \tilde{x}} + \tilde{v} \frac{\partial \tilde{u}}{\partial \tilde{y}} = -\frac{\partial \tilde{p}}{\partial \tilde{x}} + \frac{1}{Re} \left(\frac{\partial^2 \tilde{u}}{\partial \tilde{x}^2} + \frac{\partial^2 \tilde{u}}{\partial \tilde{y}^2} \right)$$

Similarly

$$\frac{\partial \tilde{v}}{\partial \tilde{t}} + \tilde{u} \frac{\partial \tilde{v}}{\partial \tilde{x}} + \tilde{v} \frac{\partial \tilde{v}}{\partial \tilde{y}} = -\frac{\partial \tilde{p}}{\partial \tilde{y}} + \frac{1}{Re} \left(\frac{\partial^2 \tilde{v}}{\partial \tilde{x}^2} + \frac{\partial^2 \tilde{v}}{\partial \tilde{y}^2} \right)$$

$\frac{\partial \tilde{u}}{\partial \tilde{x}} + \frac{\partial \tilde{v}}{\partial \tilde{y}} = 0$

Nearly the same as the unscaled version.

with $\tilde{u}(|\tilde{z}| \rightarrow \infty) = 1 \hat{e}_x$

$\tilde{u}(|\tilde{z}| = 1) = 0$

$$\underline{\underline{I}} = \rho U^2 \left[-\tilde{p} \underline{\underline{I}} + \frac{\mu}{\rho U R} (\nabla \tilde{u}^T + \nabla \tilde{u}) \right] \quad \text{and} \quad D = \rho U^2 R \int_{\partial \Omega} \tilde{\underline{\underline{I}}} \cdot \hat{n} \, d\tilde{A}$$

$$\frac{\underline{\underline{I}}}{\rho U^2} = \tilde{\underline{\underline{I}}} = -\tilde{p} \underline{\underline{I}} + \frac{1}{Re} (\nabla \tilde{u}^T + \nabla \tilde{u})$$

Define $Re = \frac{\rho U R}{\mu} = \text{Reynolds number} = \frac{\text{inertial forces}}{\text{viscous forces}}$ (after Osborne Reynolds).

- All flows with the same Reynolds numbers have the same rescaled flow.
- $\frac{D}{\rho U^2 R} = \int_{\partial \Omega} \tilde{\underline{\underline{I}}} \cdot \hat{n} \, d\tilde{A}$ depends only on Re .

Terminology: Drag coefficient $C_D = \frac{D}{\frac{1}{2} \rho U^2 R} = F(Re)$ alone.

Conclusion: Non-dimensionalization can reduce the number of independent parameters.

2. Deducing dependence on parameters without solving PDEs:

Drag on a cylinder depends on ρ, μ, R, U .

$$D = f(\rho, \mu, R, U)$$

Now use arbitrariness in the system of units.

$$\tilde{l} = \alpha l, \quad \tilde{t} = \beta t, \quad \tilde{m} = \gamma m$$

Then $\tilde{\rho} = \frac{\tilde{m}}{\tilde{l}^3} = \frac{\gamma}{\alpha^3} \frac{m}{l^3} = \frac{\gamma}{\alpha^3} \rho$

$$\tilde{\mu} = \frac{\gamma}{\alpha \beta} \mu, \quad \tilde{U} = \frac{\alpha}{\beta} U, \quad \tilde{R} = \alpha R \quad \text{and} \quad \tilde{D} = \frac{\gamma}{\beta^2} D$$

The drag relation must also hold in the transformed system.

$$\tilde{D} = f(\tilde{\rho}, \tilde{\mu}, \tilde{R}, \tilde{U})$$

Transforming back

$$\frac{\gamma}{\beta^2} D = f\left(\frac{\gamma}{\alpha^3} \rho, \frac{\gamma}{\alpha\beta} \mu, \alpha R, \frac{\alpha}{\beta} U\right) \quad \text{valid for any } \alpha, \beta, \gamma.$$

Choose $\frac{\gamma}{\alpha^3} \rho = 1$, $\frac{\alpha}{\beta} U = 1$, and $\alpha R = 1$,

i.e., $\alpha = \frac{1}{R}$, $\beta = \frac{U}{R}$ and $\gamma = \frac{1}{\rho R^3}$.

$\frac{1}{R}$ length scale
 $\frac{1}{U/R}$ time scale

Working in a system of units in which:

- fluid has unit density
- flows w/ unit speed
- cylinder has unit radius.

$$\frac{D}{\rho U^2 R} = f\left(1, \frac{1}{Re}, 1, 1\right) = \frac{1}{2} F(Re) \quad \dots \text{ same as before.}$$

We can say a little more about the behaviour of $F(Re)$ in the

limits $Re \rightarrow 0$ (viscous limit) and $Re \rightarrow \infty$ (inertial limit).

$$Re = \frac{\text{inertial forces}}{\text{viscous forces}}$$

- Inertial limit: $D = f_I(\rho, U, R) = \frac{1}{2} C_D \rho U^2 R$... viscosity "negligible".
where C_D is dimensionless

$$\Rightarrow F(Re) = C_D = \text{constant as } Re \rightarrow \infty.$$

- Viscous limit: $D = f_v(\mu, U, R) = C_v \mu U$... inertia "negligible".
where C_v is dimensionless.

$$F(Re) = \frac{2C_v}{Re} \quad \text{as } Re \rightarrow 0.$$

